

# 91258 / B0385 Natural Language Processing

Lesson 17. Recurrent Neural Networks

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# Table of Contents

- 1. Introduction
- 2. Keeping the past in mind
- 3. RNNs in Keras

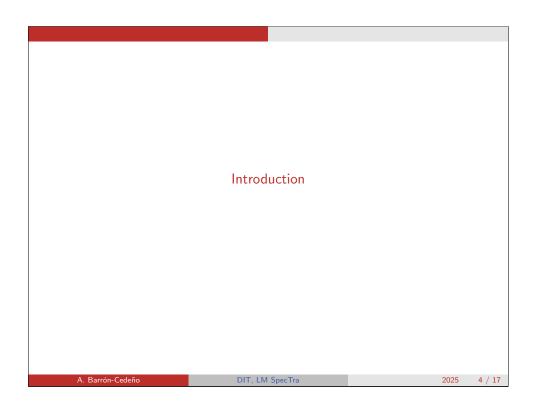
Chapter 8 of Lane et al. (2019)

• CNNs for text

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2025 2/17



### Introduction

#### **CNNs**

- Adequate for processing *full* texts (~sentences)
- Words tending to appear close to each other are spotted and play a joint role
- Longer relationships —farther than [3,4] words are ignored

#### What is missing?

- Keeping track of what happened long ago
- Memory
- Language is not an image —no snapshots
- Language is a sequence; both text and speech

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2025 5 / 1

Keeping the past in mind

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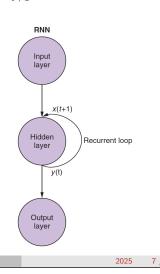
# Remembering the Past

$$W_0 W_1 W_2 W_3 \ldots W_{t-1} W_t W_{t+1}$$

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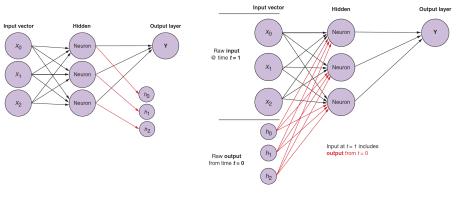
- To understand a text at time t, we need to consider what happened at time t-1, t-2, ..., t-k
- Recurrent neural nets (RRN) come into play
- RNNs combine what is happening now with what happened earlier

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# Full feed-forward networks that consider their own output Same RNN "unrolled" Input layer Hidden layer With thicken layer All three columns represent the same network (at different times) (Lane et al., 2019, p. 252) A Barrón-Sedeño DIT. LM SpecTra 2025 8 / 17

# Zooming into the *unrolled* RNN: t and t+1

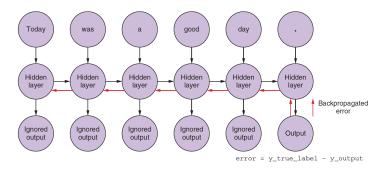


- The red arrows are just standard connections, with weights
- Now we can feed the text, one word at a time

(Lane et al., 2019, p. 252-253)

t = 0

# Backpropagation through Time: the "Vanilla" Way

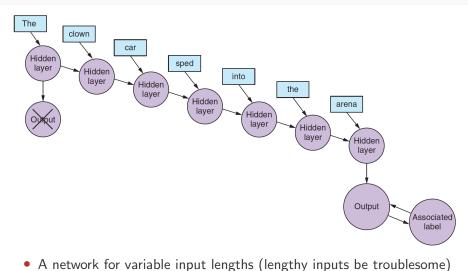


- All intermediate outputs are ignored; the loss is computed at the end
- The same chain rule is applied to do backpropagation; but this time it heads to "the past"
- The weight corrections are calculated for each t
- The combined updates are applied only until reaching t=0

(Lane et al., 2019, p. 256)

t = 1

# "Multiple inputs, one output"

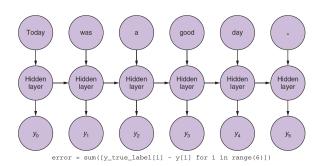


• Rather than *mutually-independent* snapshots, <sup>1</sup> there is a sense of time

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(Lane et al., 2019, p. 254)

# Backpropagation through Time: the Better Way



- We compute the loss combining all intermediate outputs
- The weight corrections are still additive: the update is applied until
  - 1. computing all errors and
  - 2. reaching back to the weight adjustments in t = 0

🗐 Let us see (Lane et al., 2019, p. 258)

#### RNNs in Keras

# RNN in Keras: further details

• A Dense layer expects a *flat* vector

- In our case:  $400 \times 50 \rightarrow 1 \times 20,000$
- Let us see.

Example derived from

https://stackoverflow.com/questions/43237124/role-of-flatten-in-keras

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## RNN in Keras: what we have so far

We have setup a simple recurrent neural network

- The input sequences have fixed length: 400 tokens (each 300D)
- Our recurrent layer contains 50 units
- The output will be  $400 \times 50$ :
  - 400 elements
  - one 50D vector each

return\_sequences=True

True return the network value at each t: 400 50D vectors

False return a single 50D vector (default)

True  $\rightarrow$  this is why we are padding



# Some parameters are "free"

embedding\_dims comes from the embedding space; hard to change, but possible: other embeddings, 1-hot

num\_neurons kind of arbitrary; can be changed

maxlen kind of arbitrary; can be changed (or neglected)

batch\_size bigger→faster (higher local minimum risk)

epochs trivial to increase (avoid starting from scratch each time)

■ Let us see.

Important: unless you have access to HPC, don't go bananas when exploring parameters (and perhaps even in that case)

Try some sensitive configurations and keep track of all the settings and outputs<sup>2</sup>

<sup>2</sup>See, for instance, Fernicola et al. (2020) **(** 

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